

Looking Below the Noise - Asteroid Hunting With the LSST

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Choosing rose-tinted glasses

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Choosing filters for large surveys





Bryce Kalmbach (University of Washington)



Jake Vanderplas (Google)

Why should I care ?





Finite observing time (and filter changes) Wavelength dependent sensitivities (sensor and atmosphere) Competing science objectives



Broadband Filters



Johnson-Cousins

SDSS

LSST

Choice of filters is somewhat adhoc

Intermediate Band Filters

Broad set of filters available and development of interference filters we can define a range of complex filters (e.g. notch or comb filters)







Bessel 2005

Information Theory



Entropy

- A measure of uncertainty in an observed variable
- Maximized when all outcomes are equally probable
- Minimized when only one outcome is non-zero

$$H(y) = -\sum_{i} p(y_i) \log_2[p(y_i)]$$



Maximum

1 bit



Lower Entropy 0.46 bits



Zero Entropy

Information Theory

Conditional Entropy

- Amount of entropy in an observation of
 Y when X = x_i is known
- How much uncertainty remains about a feature when I make a measurement of a related feature?
- Example:
 - Y is the probability of illness
 - X is age

$$H(Y|X) \equiv \sum_{i,j} P(x_j)H(y_i|x_j)$$



Information Theory

Information Gain (IG)

- Difference between total entropy and average conditional entropy
 - Average effectiveness of a measurement X in supplying information about a feature, Y
- The more information gain we can derive from a measurement of X then the more this measurement reduces our uncertainty in another property Y

IG(Y|X) = H(Y) - H(Y|X)



Modeling type given colorExample 1:

 Measure colors to distinguish between two types of galaxy spectra





Modeling type given color

• Example 1:

 Measure colors to distinguish between two types of galaxy spectra





Designing filters for photo-zExample 2:

- Measure IG(YIX)
 - X is color, Y is redshift
- Use a realistic galaxy spectrum and prior that peaks at z=0.55





Colors and redshift

- The color distribution is approximated by a Gaussian affected by the signal to noise of the galaxy
- Optimal filters maximize the chance that a galaxy observed with a given color is at a specific redshift
 - Especially for redshifts near the peak of the prior



Realistic Experiments



- Calculated galaxy color distributions using 10 templates at 46 redshift bins from $0 < z \le 2.3$
- Template magnitudes were normalized to *i* = 25
- Used prior appropriate for fainter galaxies



What would you observe after the LSST finished?

- First, looked at optimal 7th filter to add to LSST
- Optimal filter spans the Balmer break near the peak of the prior
- Improves information gain for LSST filters by 4%

Redshift prior peak z~0.92. Info Gain: 2.83 out of 5.36 bits (LSST=2.71)



What would you observe after the LSST finished?

- Changing the prior leads to a change in the filter
 - Remains located near the Balmer break at the peak redshift



Optimal shape for a filter

- What shape should a filter have
- Set a fixed ratio between top and bottom width of trapezoidal filters
- Found that more top-hat like filters are better for photo-z







Improving on LSST



Photometric Redshifts (photo-z)



 Photo-Z relies upon features of spectral energy distribution (SED) moving through different photometric filters



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photo-z Testing



- Sample catalog of 245,106 training objects and 50,000 test objects
 - Redshifts: $0 < z \le 2.3$
- Use Color Matched Nearest Neighbor (CMNN) method (Graham et al. (2018))
 - Returns nearest neighbor in color space measured with Mahalanobis distance
- Compared 4 metrics
 - o Bias
 - Standard Deviation
 - Standard Deviation of Interquartile Range (IQR)
 - Outlier Fraction

Application to photo-z



Used simulated catalogs of galaxy photometry with different filter selections



Where next?



- This can be applied to stellar colors or any distribution
- Build and optimize a series of comb filters (>dimensions)
- Integrate near-infrared filters with the LSST

...we also find asteroids



